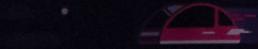


# What's Inside the Box?

Comparing Data Storage Across Frameworks

@ray\_deck

# CHAIN REACT



SPECIAL THANKS TO

 SQUARESPACE

PRESENTED BY

 INFINITE RED



CHAIN REACT

SPECIAL THANKS TO

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# Code as Data

PyTorch  
Keras  
TensorFlow  
TensorFlow Lite  
CoreML



The PyTorch logo is centered on a red background. It consists of the word "PYTORCH" in white, bold, sans-serif capital letters. The letter "T" is replaced by an orange flame-like shape with a small blue drop at the top. The background features a network of light gray lines connecting numerous small, semi-transparent purple dots, creating a sense of connectivity and data flow.

P Y T O R C H

# Best practices

## Recommended approach for saving a model

There are two main approaches for serializing and restoring a model.

The first (recommended) saves and loads only the model parameters:

```
torch.save(the_model.state_dict(), PATH)
```

Then later:

```
the_model = TheModelClass(*args, **kwargs)
the_model.load_state_dict(torch.load(PATH))
```

The second saves and loads the entire model:

```
torch.save(the_model, PATH)
```

Then later:

```
the_model = torch.load(PATH)
```

However in this case, the serialized data is bound to the specific classes and the exact directory structure used, so it can break in various ways when used in other projects, or after some serious refactors.

# Serialization

[pytorch.org/  
docs/  
stable/  
notes/  
serialization.html](https://pytorch.org/docs/stable/notes/serialization.html)

## Table Of Contents

- [pickle — Python object serialization](#)
  - Relationship to other Python modules
    - Comparison with [marshal](#)
    - Comparison with [json](#)
  - Data stream format
  - Module Interface
  - What can be pickled and unpickled?
  - Pickling Class Instances
    - Persistence of External Objects
    - Dispatch Tables
    - Handling Stateful Objects
  - Restricting Globals
  - Performance
  - Examples

Previous topic

Data Persistence

Next topic

[copyreg](#) — Register [pickle](#) support functions

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[Report a Bug](#)

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# pickle — Python object serialization

**Source code:** [Lib/pickle.py](#)

The `pickle` module implements binary protocols for serializing and de-serializing a Python object structure. “*Pickling*” is the process whereby a Python object hierarchy is converted into a byte stream, and “*unpickling*” is the inverse operation, whereby a byte stream (from a [binary file](#) or [bytes-like object](#)) is converted back into an object hierarchy. Pickling (and unpickling) is alternatively known as “serialization”, “marshalling,” [1] or “flattening”; however, to avoid confusion, the terms used here are “pickling” and “unpickling”.

**Warning:** The `pickle` module is not secure against erroneous or maliciously constructed data. Never unpickle data received from an untrusted or unauthenticated source.

## Relationship to other Python modules

### Comparison with `marshal`

Python has a more primitive serialization module called `marshal`, but in general `pickle` should always be the preferred way to serialize Python objects. `marshal` exists primarily to support Python’s `.pyc` files.

The `pickle` module differs from `marshal` in several significant ways:

- The `pickle` module keeps track of the objects it has already serialized, so that later references to the same object won’t be serialized again. `marshal` doesn’t do this.

This has implications both for recursive objects and object sharing. Recursive objects are objects that contain references to themselves. These are not handled by `marshal`, and in fact, attempting to `marshal` recursive objects will crash your Python interpreter. Object sharing happens when there are multiple references to the same object in different places in the object hierarchy being serialized. `pickle` stores such objects only once, and ensures that all other references point to the master copy. Shared objects remain shared, which can be very important for mutable objects.

- `marshal` cannot be used to serialize user-defined classes and their instances. `pickle` can save and restore class instances transparently, however the class

# Pickle

[docs.python.org/3/library/pickle.html](https://docs.python.org/3/library/pickle.html)



Keras

JSON + HDF



EXPLORER

## OPEN EDITORS

{ model.json }

## NOTEBOOK

▶ .ipynb\_checkpoints

▶ bottlenecks

▶ preview

▶ source

≡ base.h5



{ model.json }

mouse.jpg

≡ output.h5

≡ Ray Keras TL.ipynb

≡ Rebuild inception.ipynb

≡ terminal.h5

mouse.jpg

testout.jpg



1

{ model.json }

```
1  {
2      "class_name": "Sequential",
3      "config": [
4          {
5              "class_name": "Model",
6              "config": {
7                  "name": "inception_v3",
8                  "layers": [
9                      {
10                         "name": "input_2",
11                         "class_name": "InputLayer",
12                         "config": {
13                             "batch_input_shape": [
14                                 null,
15                                 150,
16                                 150,
17                                 3
18                             ],
19                             "dtype": "float32",
20                             "sparse": false,
21                             "name": "input_2"
22                         },
23                         "inbound_nodes": []
24                     },
25                     {
26                         "name": "conv2d_95",
27                         "class_name": "Conv2D",
28                         "config": {
29                             "name": "conv2d_95",
30                             "trainable": true,
31                             "filters": 32,
32                             "kernel_size": [
33                                 3,
34                                 3
35                             ]
36                         }
37                     }
38                 ]
39             }
40         }
41     ]
42 }
```



# HDFView 2.14

File Window Tools Help



Recent Files

C:\Users\ray deck.E55DEVELOPMENT\Documents\notebookoutput.h5

Clear Text

kernel:0 at /model\_weights/inception\_v3/conv2d\_130/ [output.h5 in C:\Users\ray deck.E55DEVEL...]

Table 0 127

0-based

	0
0	-0.0064085...
1	-0.0100630...
2	-0.0352805...
3	-0.02917963
4	-0.0185456...
5	-0.0019083...
6	-0.0027629...

kernel:0 (9218232, 2)

32-bit floating-point, 7 x 1 x 128 x 128

Number of attributes = 0

Log Info Metadata



Recent Files C:\Users\ray deck.E55DEVELOPMENT\Documents\notebook\output.h5

5 output.h5  
model\_weights  
inception\_v3  
sequential\_1  
dense\_1  
bias:0  
kernel:0

kernel:0 at /model\_weights/sequential\_1/dense\_1/

Table

	0	1
0	-0.21443711	0.22328563
1	-0.04017427	0.0483091...
2	-0.12604576	0.09689116
3	-0.21185246	0.1902625
4	-0.0385228...	0.0301027...
5	-0.21162167	0.22007269
6	0.0308830...	-0.0409881
7	-0.04188589	0.0207552...
8	0.11872259	-0.10168603
9	0.0637263...	-0.08402596
10	-0.04963228	0.0529383...
11	0.12830532	-0.10552378

kernel:0 (87702216, 2)  
32-bit floating-point, 18432 x 2  
Number of attributes = 0

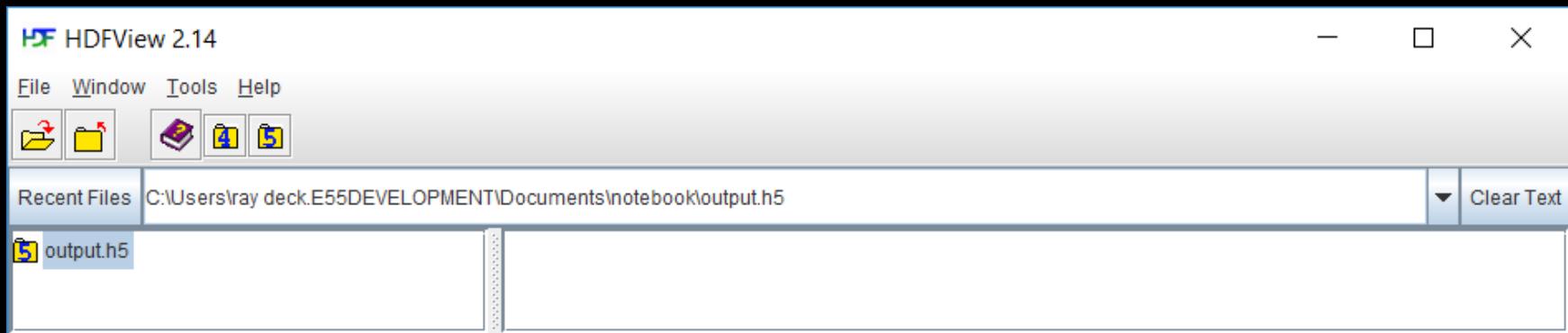
# HDFView

[portal.hdfgroup.org/display/support/Download+HDFView](http://portal.hdfgroup.org/display/support/Download+HDFView)

# Panoply

[www.giss.nasa.gov/tools/panoply/](http://www.giss.nasa.gov/tools/panoply/)

# JSON in HDF5



```
/ (96)
Group size = 1
Number of attributes = 3
    backend = tensorflow
    keras_version = 2.0.8
    model_config = {"class_name": "Sequential", "config": [{"class_name": "Model", "config": {"name": "inception_v3", "layers": [{"name": "input_2", "class_name": "InputLayer", "config": {"batch_input_shape": [null, 150, 150, 3], "dtype": "float32", "sparse": false, "name": "input_2"}, "inbound_nodes": []}, {"name": "conv2d_95", "class_name": "Conv2D", "config": {"name": "conv2d_95", "trainable": true, "filters": 32, "kernel_size": [3, 3], "strides": [2, 2], "padding": "valid", "data_format": "channels_last", "dilation_rate": [1, 1], "activation": "linear", "use_bias": false, "kernel_initializer": {"class_name": "VarianceScaling", "config": {"scale": 1.0, "mode": "fan_avg", "distribution": "uniform", "seed": null}}, "bias_initializer": {"class_name": "Zeros", "config": {}}, "kernel_regularizer": null, "bias_regularizer": null, "activity_regularizer": null, "kernel_constraint": null, "bias_constraint": null}, "inbound_nodes": [[[{"name": "input_2", "order": 0}], {"name": "batch_normalization_95", "class_name": "BatchNormalization", "config": {"name": "batch_normalization_95", "trainable": true, "axis": 3, "momentum": 0.99, "epsilon": 0.001, "center": true, "scale": false, "beta_initializer": {"class_name": "Zeros", "config": {}}, "gamma_initializer": {"class_name": "Ones", "config": {}}, "moving_mean_initializer": {"class_name": "Zeros", "config": {}}, "moving_variance_initializer": {"class_name": "Ones", "config": {}}, "beta_regularizer": null, "gamma_regularizer": null, "beta_constraint": null, "gamma_constraint": null}, "inbound_nodes": [[[{"name": "conv2d_95", "order": 0}], {"name": "activation_95", "class_name": "Activation", "config": {"name": "activation_95", "trainable": true, "activation": "relu"}, "inbound_nodes": [[[{"name": "batch_normalization_95", "order": 0}], {"name": "conv2d_96", "class_name": "Conv2D", "config": {"name": "conv2d_96", "trainable": true, "filters": 32, "kernel_size": [3, 3], "strides": [1, 1], "padding": "valid", "data_format": "channels_last", "dilation_rate": [1, 1], "activation": "linear", "use_bias": false, "kernel_initializer": {"class_name": "VarianceScaling", "config": {"scale": 1.0, "mode": "fan_avg", "distribution": "uniform", "seed": null}}, "bias_initializer": {"class_name": "Zeros", "config": {}}, "kernel_regularizer": null, "bias_regularizer": null, "activity_regularizer": null, "kernel_constraint": null, "bias_constraint": null}, "inbound_nodes": [[[{"name": "activation_95", "order": 0}], {"name": "batch_normalization_96", "class_name": "BatchNormalization", "config": {"name": "batch_normalization_96", "trainable": true, "axis": 3, "momentum": 0.99, "epsilon": 0.001, "center": true, "scale": false, "beta_initializer": {"class_name": "Zeros", "config": {}}, "gamma_initializer": {"class_name": "Ones", "config": {}}, "moving_mean_initializer": {"class_name": "Zeros", "config": {}}, "moving_variance_initializer": {"class_name": "Ones", "config": {}}, "beta_regularizer": null, "gamma_regularizer": null, "beta_constraint": null, "gamma_constraint": null}, "inbound_nodes": [[[{"name": "conv2d_96", "order": 0}], {"name": "activation_96", "class_name": "Activation", "config": {"name": "activation_96", "trainable": true, "activation": "relu"}, "inbound_nodes": [[[{"name": "batch_normalization_96", "order": 0}], {"name": "conv2d_97", "class_name": "Conv2D", "config": {"name": "conv2d_97", "trainable": true, "filters": 64, "kernel_size": [3, 3], "strides": [1, 1], "padding": "same", "data_format": "channels_last", "dilation_rate": [1, 1], "activation": "linear", "use_bias": false, "kernel_initializer": {"class_name": "VarianceScaling", "config": {"scale": 1.0, "mode": "fan_avg", "distribution": "uniform", "seed": null}}, "bias_initializer": {"class_name": "Zeros", "config": {}}, "kernel_regularizer": null, "bias_regularizer": null, "activity_regularizer": null, "kernel_constraint": null, "bias_constraint": null}, "inbound_nodes": [[[{"name": "activation_96", "order": 0}], {"name": "batch_normalization_97", "class_name": "BatchNormalization", "config": {"name": "batch_normalization_97", "trainable": true, "axis": 3, "momentum": 0.99, "epsilon": 0.001, "center": true, "scale": false, "beta_initializer": {"class_name": "Zeros", "config": {}}, "gamma_initializer": {"class_name": "Ones", "config": {}}, "moving_mean_initializer": {"class_name": "Zeros", "config": {}}, "moving_variance_initializer": {"class_name": "Ones", "config": {}}, "beta_regularizer": null, "gamma_regularizer": null, "beta_constraint": null, "gamma_constraint": null}, "inbound_nodes": [[[{"name": "conv2d_97", "order": 0}], {"name": "activation_97", "class_name": "Activation", "config": {"name": "activation_97", "trainable": true, "activation": "relu"}, "inbound_nodes": []}]]]]]
```





**protobuf**  
Protocol Buffers

Protocol buffers are a language-neutral, platform-neutral extensible mechanism for serializing structured data.

HOME

GUIDES

REFERENCE

SUPPORT

```
message Person {    •• ⓘ  
    required string name = 1;  
    required int32 id = 2;  
    optional string email = 3;  
}
```

```
Person john = Person.newBuilder()    •• ⓘ  
    .setId(1234)  
    .setName("John Doe")  
    .setEmail("jdoe@example.com")  
    .build();  
output = new FileOutputStream(args[0]);  
john.writeTo(output);
```

```
Person john;    •• ⓘ  
fstream input(argv[1],  
    ios::in | ios::binary);  
john.ParseFromIstream(&input);  
id = john.id();  
name = john.name();  
email = john.email();
```

## What are protocol buffers?

Protocol buffers are Google's language-neutral, platform-neutral, extensible mechanism for serializing structured data – think

## Pick your favorite language

Protocol buffers currently support generated code in Java, Python, Objective-C, and C++. With our new proto3 language version, you can also work with Go, Ruby, and C#, with more languages to come.

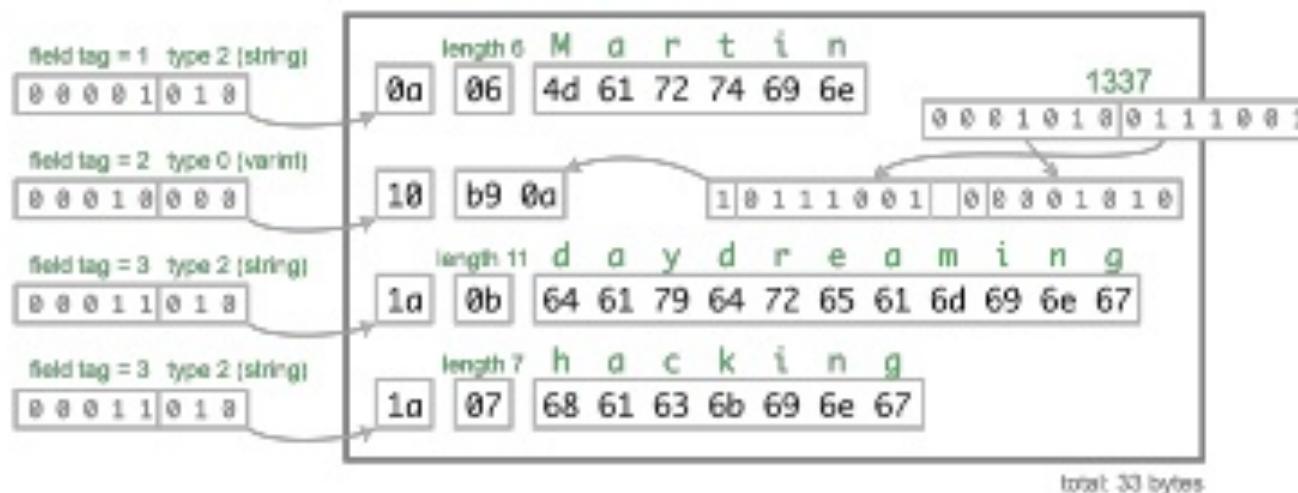
## How do I start?

1. [Download](#) and install the protocol buffer compiler.
2. Read the [overview](#).
3. Try the [tutorial](#) for your chosen

# Message

Person.json	Person.proto
<pre>{     "userName": "Martin",     "favouriteNumber": 1337,     "interests": ["daydreaming", "hacking"] }</pre>	<pre>message Person {     required string user_name      = 1;     optional int64 favourite_number = 2;     repeated string interests       = 3; }</pre>

## Protocol Buffers



Branch: master ▾

[tensorflow](#) / [tensorflow](#) / [core](#) / [protobuf](#) /

Create new file



tensorflower-gardener Automated rollback of commit cb98ceb ⋮

..

[checkpointable\\_object\\_graph.proto](#) Start moving Checkpointable utilities toward core[cluster.proto](#) Merge changes from github.[config.proto](#) Introduce the abstraction of RunHandler which each DirectSession can ...[control\\_flow.proto](#) Merge changes from github.[critical\\_section.proto](#) Merge changes from github.[debug.proto](#) tfdbg: Add adjustable limit to total bytes dumped to disk[device\\_properties.proto](#) Merge changes from github.[eager\\_service.proto](#) Push tensors from client to workers.[master.proto](#) Merge changes from github.[master\\_service.proto](#) Merge changes from github.[meta\\_graph.proto](#) Merge changes from github.[named\\_tensor.proto](#) Merge changes from github.[queue\\_runner.proto](#) Merge changes from github.[replay\\_log.proto](#) Implement TF graph capture.[rewriter\\_config.proto](#) Automated rollback of commit cb98ceb[saved\\_model.proto](#) Merge changes from github.[saver.proto](#) Merge changes from github.[tensor\\_bundle.proto](#) Merge changes from github.[tensorflow\\_server.proto](#) Make protocol used in estimator customizable.

github.com/tensorflow/tree/master/tensorflow/core/protobuf

 yongtang Add go\_package to proto definition files (#17262)

a44996a on May 2

6 contributors 

57 lines (51 sloc) | 2.2 KB

Raw Blame History   

```
1 syntax = "proto3";
2
3 package tensorflow;
4 option cc_enable_arenas = true;
5 option java_outer_classname = "GraphProtos";
6 option java_multiple_files = true;
7 option java_package = "org.tensorflow.framework";
8 option go_package = "github.com/tensorflow/tensorflow/tensorflow/go/core/framework";
9 import "tensorflow/core/framework/node_def.proto";
10 import "tensorflow/core/framework/function.proto";
11 import "tensorflow/core/framework/versions.proto";
12
13 // Represents the graph of operations
14 message GraphDef {
15     repeated NodeDef node = 1;
16
17     // Compatibility versions of the graph. See core/public/version.h for version
18     // history. The GraphDef version is distinct from the TensorFlow version, and
19     // each release of TensorFlow will support a range of GraphDef versions.
20     VersionDef versions = 4;
21 }
```

# Protobuf Viewer

MacOS App Store

# Protobuf Editor

[sourceforge.net/projects/protobufeditor/](http://sourceforge.net/projects/protobufeditor/)

▼ 0	100	Length-delimited	embedded-message	▽
█ 1	Varint	uint64	▽	32
█ 2	Varint	uint64	▽	16
█ 10	Varint	uint64	▽	1
█ 20	Length-delimited	string	▽	""
█ 30	Length-delimited	string	▽	""
█ 40	Length-delimited	string	▽	""
▼ 0	50	Length-delimited	embedded-message	▽
▼ 0	1	Length-delimited	embedded-message	▽
▼ 0	10	Length-delimited	embedded-message	▽
█ 1	Varint	uint64	▽	1
█ 2	Varint	uint64	▽	1
▼ 0	10	Length-delimited	embedded-message	▽
█ 1	Varint	uint64	▽	1
█ 2	Varint	uint64	▽	1
█ 70	Varint	uint64	▽	1
▼ 0	90	Length-delimited	embedded-message	▽
█ 1	Length-delimited	bytes	▽	"\x95\x9c\x1b\xbe\xe5\x5e\xff\xbd\x9e\xe9\x7a\xbe\x72\xae\x71\xbd\x66\x96\x11\x3e\x8c\xcb\x74\xbe\x15\x a7\xd3\x3"
▼ 0	91	Length-delimited	embedded-message	▽
█ 1	Length-delimited	bytes	▽	"\xc1\x17\xff\xbd\x77\xf1\x17\x3c\x58\x1b\x a4\x3d\x40\x6c\xf7\x3c\xeb\x62\x41\x3e\x e1\x98\x3d\xbd\x64\x90\x04\x3"
▼ 0	1	Length-delimited	embedded-message	▽
█ 1	Length-delimited	embedded-message	▽	
█ 2	Length-delimited	string	▽	"InstanceNormalization_8"
█ 3	Length-delimited	string	▽	"SpatialConvolution_7"
► 0	160	Length-delimited	embedded-message	▽
▼ 0	1	Length-delimited	embedded-message	▽
█ 1	Length-delimited	string	▽	"ReLU_9"
█ 2	Length-delimited	string	▽	"InstanceNormalization_8"
█ 3	Length-delimited	string	▽	"ReLU_9"
▼ 0	130	Length-delimited	embedded-message	▽
█ 1	Length-delimited	string	▽	""





▼ FlatBuffers

- ▶ Overview
- ▶ Programmer's Guide
- ▶ Platform / Language / Feature support
- ▶ Benchmarks
- ▶ FlatBuffers white paper
- ▶ FlatBuffers internals
- ▶ Grammar of the schema language
- ▶ API Reference
- ▶ Contributing

# FlatBuffers

## Overview

[FlatBuffers](#) is an efficient cross platform serialization library for C++, C#, C, Go, Java, JavaScript, Lobster, Lua, TypeScript, PHP, Python, and Rust. It was originally created at Google for game development and other performance-critical applications.

It is available as Open Source on [GitHub](#) under the Apache license, v2 (see LICENSE.txt).

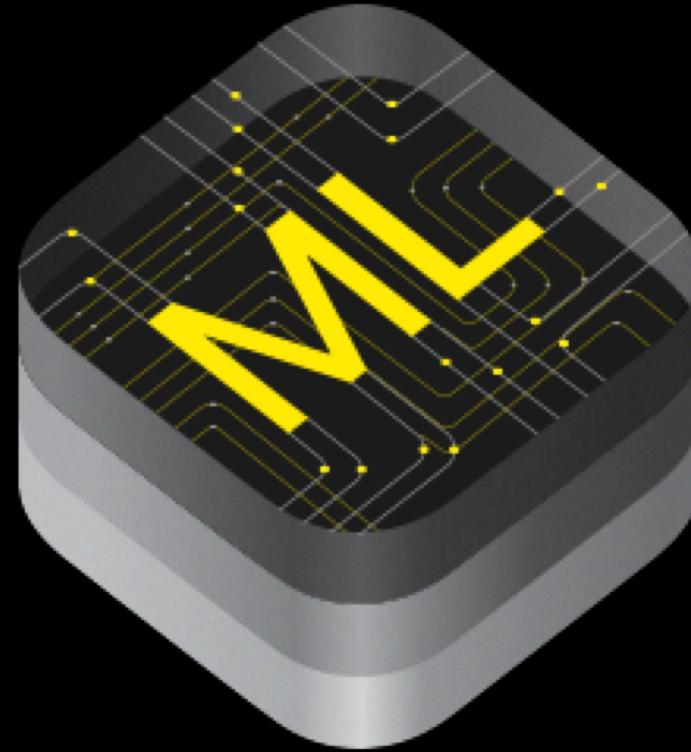
## Why use FlatBuffers?

- **Access to serialized data without parsing/unpacking** - What sets FlatBuffers apart is that it represents hierarchical data in a flat binary buffer in such a way that it can still be accessed directly without parsing/unpacking, while also still supporting data structure evolution (forwards/backwards compatibility).
- **Memory efficiency and speed** - The only memory needed to access your data is that of the buffer. It requires 0 additional allocations (in C++, other languages may vary). FlatBuffers is also very suitable for use with mmap (or streaming), requiring only part of the buffer to be in memory. Access is close to the speed of raw struct access with only one extra indirection (a kind of vtable) to allow for format evolution and optional fields. It is aimed at projects where spending time and space (many memory allocations) to be able to access or construct serialized data is undesirable, such as in games or any other performance sensitive applications. See the [benchmarks](#) for details.
- **Flexible** - Optional fields means not only do you get great forwards and backwards compatibility (increasingly important for long-lived games: don't have to update all data with each new version!). It also means you have a lot of choice in what data you write and what data you don't, and how you design data structures.
- **Tiny code footprint** - Small amounts of generated code, and just a single small header as the minimum dependency, which is very easy to integrate. Again, see the benchmark section for details.
- **Strongly typed** - Errors happen at compile time rather than manually having to write repetitive and error prone run-time checks. Useful code can be generated for you.
- **Convenient to use** - Generated C++ code allows for terse access & construction code. Then there's optional

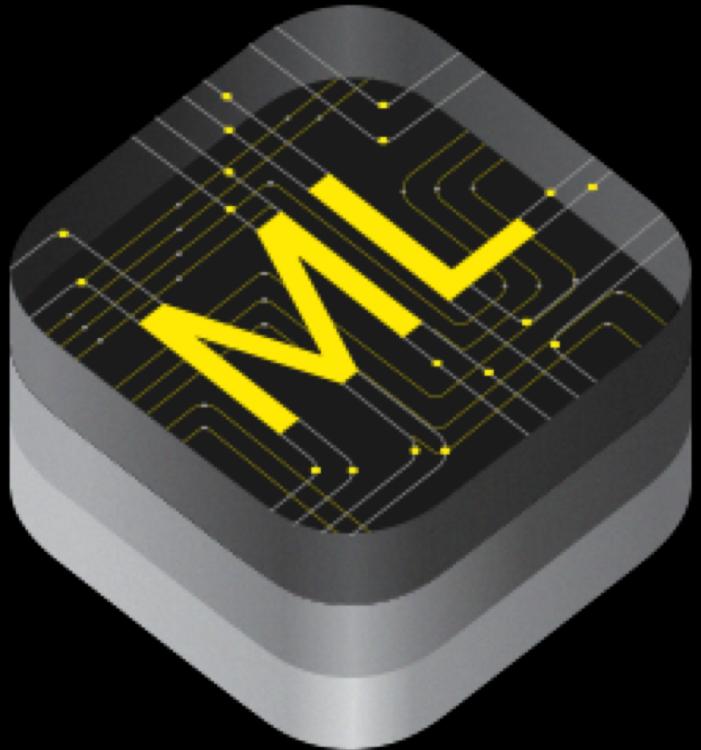
google.github.io/  
flatbuffers/

```
63 name:string; // For debugging and importing back into tensorflow.
64 quantization:QuantizationParameters; // Optional.
65 }
66
67 // A list of builtin operators. Builtin operators are slightly faster than custom
68 // ones, but not by much. Moreover, while custom operators accept an opaque
69 // object containing configuration parameters, builtins have a predetermined
70 // set of acceptable options.
71 enum BuiltinOperator : byte {
72     ADD = 0,
73     AVERAGE_POOL_2D = 1,
74     CONCATENATION = 2,
75     CONV_2D = 3,
76     DEPTHWISE_CONV_2D = 4,
77     // DEPTH_TO_SPACE = 5,
78     // DEQUANTIZE = 6,
79     EMBEDDING_LOOKUP = 7,
80     // FLOOR = 8,
81     FULLY_CONNECTED = 9,
82     HASHTABLE_LOOKUP = 10,
83     L2_NORMALIZATION = 11,
84     L2_POOL_2D = 12,
85     LOCAL_RESPONSE_NORMALIZATION = 13,
86     LOGISTIC = 14,
87     LSH_PROJECTION = 15,
88     LSTM = 16,
89     MAX_POOL_2D = 17,
90     // MUL = 18,
91     RELU = 19,
92     // RELU1=20,
93     RELU6 = 21,
94     RESHAPE = 22,
95     RESIZE_BILINEAR = 23,
96     RNN = 24,
97     SOFTMAX = 25,
98     SPACE_TO_DEPTH = 26,
99     SVDF = 27,
```

github.com/  
tensorflow/  
tensorflow/  
blob/  
master/  
tensorflow/  
contrib/  
lite/  
schema/  
schema\_v3.fbs



[github.com/  
apple/  
coremltools/  
tree/  
master/  
mlmodel/  
format](https://github.com/apple/coremltools/tree/master/mlmodel/format)



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Branch: master ▾

[coremltools / mlmodel / format /](#)[Create new file](#)[Upload files](#)[Find file](#)[History](#)

 Sohaib Qureshi	Consolidate changes for coremltools 2.0 public release	Latest commit f11c43e on Aug 29
..		
<a href="#">ArrayFeatureExtractor.proto</a>	Add Linux build support	a year ago
<a href="#">BayesianProbitRegressor.proto</a>	Consolidated changes from 2.0b1 release	3 months ago
<a href="#">CategoricalMapping.proto</a>	Add Linux build support	a year ago
<a href="#">CustomModel.proto</a>	Consolidated changes from 2.0b1 release	3 months ago
<a href="#">DataStructures.proto</a>	Add Linux build support	a year ago
<a href="#">DictVectorizer.proto</a>	minor proto sp fixes	8 months ago
<a href="#">FeatureTypes.proto</a>	Consolidated changes from 2.0b1 release	3 months ago
<a href="#">FeatureVectorizer.proto</a>	Add Linux build support	a year ago
<a href="#">GLMClassifier.proto</a>	Add Linux build support	a year ago
<a href="#">GLMRegressor.proto</a>	Add Linux build support	a year ago
<a href="#">IdentityMapper</a>	Add Linux build support	a year ago

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<a href="#">BayesianProbitRegressor.proto</a>	Consolidated changes from 2.0b1 release	3 months ago
<a href="#">CategoricalMapping.proto</a>	Add Linux build support	a year ago
<a href="#">CustomModel.proto</a>	Consolidated changes from 2.0b1 release	3 months ago
<a href="#">DataStructures.proto</a>	Add Linux build support	a year ago
<a href="#">DictVectorizer.proto</a>	minor proto sp fixes	8 months ago
<a href="#">FeatureTypes.proto</a>	Consolidated changes from 2.0b1 release	3 months ago
<a href="#">Featurevectorizer.proto</a>	Add Linux build support	a year ago
<a href="#">GLMClassifier.proto</a>	Add Linux build support	a year ago
<a href="#">GLMRegressor.proto</a>	Add Linux build support	a year ago
<a href="#">Identityproto</a>	Add Linux build support	a year ago

```
30 }
31
32 /**
33 * The image feature type.
34 */
35 message ImageFeatureType {
36     // Assumes raw (decompressed) format
37     enum ColorSpace {
38         INVALID_COLOR_SPACE = 0;
39         GRayscale = 10; // 8 bits per pixel
40         RGB = 20;       // 32 bits per pixel: RGBA with A channel ignored
41         BGR = 30;       // 32 bits per pixel: BGRA with A channel ignored
42     }
43
44     message ImageSize {
45         uint64 width = 1;
46         uint64 height = 2;
47     }
48
49     message EnumeratedImageSizes {
50         repeated ImageSize sizes = 1;
51     }
52
53     message ImageSizeRange {
54         SizeRange widthRange = 1;
55         SizeRange heightRange = 2;
56     }
57
58     // The required or default image size is width x height
59     //
60     // If specificationVersion <= 2 or SizeFlexibility is empty,
61     // width x height is the required fixed image size
```

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Branch: master ▾

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 Sohaib Qureshi	Consolidate changes for coremltools 2.0 public release	Latest commit f11c43e on Aug 29
..		
 ArrayFeatureExtractor.proto	Add Linux build support	a year ago
 BayesianProbitRegressor.proto	Consolidated changes from 2.0b1 release	3 months ago
 CategoricalMapping.proto	Add Linux build support	a year ago
 CustomModel.proto	Consolidated changes from 2.0b1 release	3 months ago
 DataStructures.proto	Add Linux build support	a year ago
 DictVectorizer.proto	minor proto sp fixes	8 months ago
 FeatureTypes.proto	Consolidated changes from 2.0b1 release	3 months ago
 FeatureVectorizer.proto	Add Linux build support	a year ago
 GLMClassifier.proto	Add Linux build support	a year ago
 GLMRegressor.proto	Add Linux build support	a year ago
 IdentityMapper	Add Linux build support	a year ago

```
11 package CoreML.Specification;
12
13 /**
14  * A categorical mapping.
15  *
16  * This allows conversion from integers to strings, or from strings to integers.
17  */
18 message CategoricalMapping {
19     oneof MappingType {
20         // Conversion from strings to integers
21         StringToInt64Map stringToInt64Map = 1;
22
23         // Conversion from integer to string
24         Int64ToStringMap int64ToStringMap = 2;
25     }
26
27 /**
28  * The value returned if an input is not contained in the map above.
29  * If one of these is not set, then an error is raised on an unknown input.
30  */
31     oneof ValueOnUnknown {
32         // Default output when converting from an integer to a string.
33         string strValue = 101;
34
35         // Default output when converting from an string to an integer.
36         int64 int64Value = 102;
37     }
38 }
```

```
let c = MLModel.compile(url: u)
let m = MLModel(url: c)
let d:[String:Any] = ["input": image]
let dfpin = MLDictionaryFeatureProvider(dictionary: d)
let fp = m.predict(dfp)
let dfpout = fp.featureValue(for: "labels")
let dic = dfpout.dictionaryValue
let topResult = dic.first()
```



**Vision and natural language  
Custom data  
Built in Swift**

Ready to continue Create ML Playground

Create ML Playground

```
1 import Foundation
2 import CreateMLUI
3
4 // A visualizer to help build ImageClassifiers
5 let builder = MLImageClassifierBuilder()
6
7 // Start the playground's live view to display the
8 // visualizer, to train the model within the playground.
9 builder.showInLiveView()
```

11

LIVE View > Create ML Playground.playground (Live View)



ImageClassifier

Model accuracy

92%

Training

Evaluation



Predicted  
many flavors



Predicted  
many flavors



coremltools/VisionFeaturePrint.p GitHub, Inc. [US] https://github.com/apple/coremlt... +

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 znation Consolidated changes from 2.0b1 release e90500d on Jul 3

1 contributor

38 lines (29 sloc) | 1.05 KB Raw Blame History

```
1 // Copyright (c) 2018, Apple Inc. All rights reserved.
2 //
3 // Use of this source code is governed by a BSD-3-clause license that can be
4 // found in LICENSE.txt or at https://opensource.org/licenses/BSD-3-Clause
5
6 syntax = "proto3";
7 option optimize_for = LITE_RUNTIME;
8
9 package CoreML.Specification.CoreMLModels;
10
11 /**
12 * A model which takes an input image and outputs an array of features
13 */
```

```
16  
17 // Specific vision feature print types  
18  
19 // Scene extracts features useful for identifying contents of natural images  
20 // in both indoor and outdoor environments  
21 message Scene {  
22     enum SceneVersion {  
23         SCENE_VERSION_INVALID = 0;  
24         // VERSION_1 is available on iOS, tvOS 12.0+, macOS 10.14+  
25         // It uses a 299x299 input image and yields a 2048 float feature vector  
26         SCENE_VERSION_1 = 1;  
27     }  
28  
29     SceneVersion version = 1;  
30 }  
31  
32 // Vision feature print type  
33 oneof VisionFeaturePrintType {  
34     Scene scene = 20;  
35 }  
36
```

Quo Vadis?



Conference  
React Native EU 2018

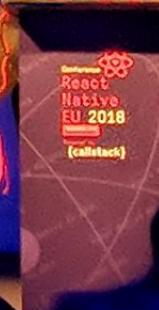
f /reactnativeeu

v @react\_native\_eu

# Coming Soon



Powered by  
**{callstack}**



# Thank You

@ray\_deck

[github.com/rhdeck/papis-2018](https://github.com/rhdeck/papis-2018)